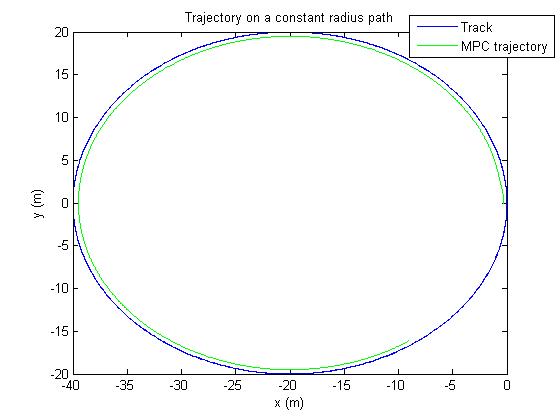
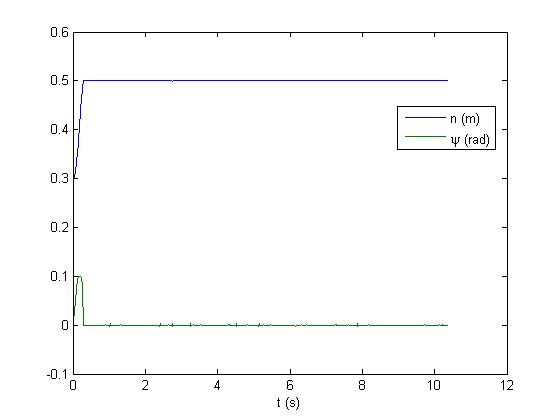
# Section 6.3

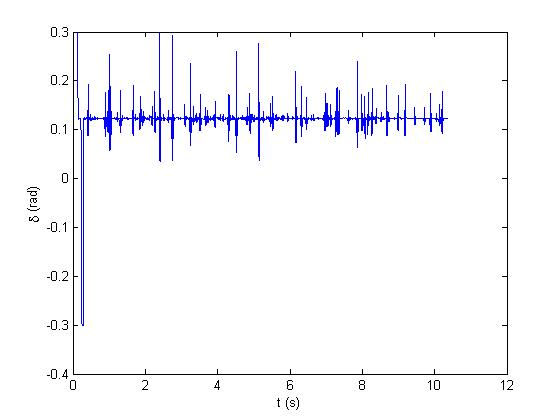
For constant radius section:



Lateral error and heading deviation plot

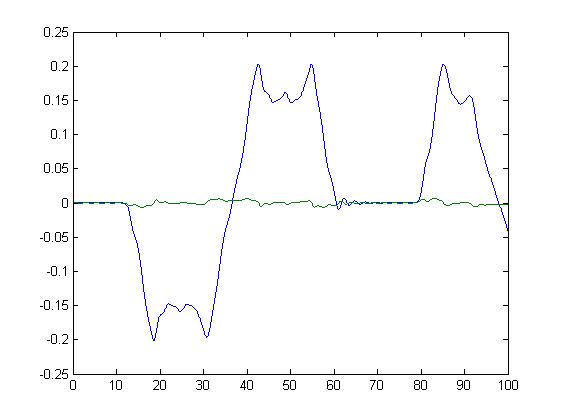


Plot of control effort



In the undulating path:

Time history of error and yaw



Control history